

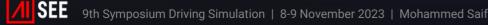
ARTIFICIAL INTELLIGENCE ENHANCING VEHICLE VISION IN LOW VISIBILITY CONDITIONS

ANSYS GERMANY GmbH Mohammed Saif

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HOW CAN WE ENSURE THAT **AUTOMATED VEHICLES DRIVE RELIABLY** EVEN IN ADVERSE WEATHER CONDITIONS?



THE GOAL



Develop a robust and fault-tolerant novel sensing technology and associated AI

Enable automated driving in all relevant
weather & lighting conditions (snow, heavy rain, fog)

Permit safe driving **24h / 365-days**



THE CHALLENGE



• Currently commercialization of automated vehicles is difficult due to their inability to drive under any relevant weather and lighting conditions.

• Testing takes place in **small designated areas with good** weather conditions.

• Prototypes **struggle or completely fail** in adverse weather.



THE INNOVATION



• Prepare the broad market entry of automated vehicles

Extend the Operational Design Domain (ODD) of today's systems

• Make prototypes functional in real driving conditions.



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THE CONCEPT



• High resolution adaptive all-weather sensor suite with novel sensors

• Al platform for predictive detection of prevailing environmental conditions including signal enhancement and sensor adaptation

 Novel simulation path which allows to realistically simulate adverse weather near the sensor to adapt and test the system on both real and artificially generated road scenes

O High definition maps with dynamic layers adaptable to changing weather conditions

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ALL WEATHER MULTI-SENSOR PERCEPTION SYSTEM SUPPORTED BY AI



The AI platform will include the development of:

O Multisensory data fusion approach: Deep Sparse Multi-Scale Convolutional Neural Networks

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• **Predictive detection** of prevailing environmental conditions and sensor adaptation

O Signal enhancement via Generative Adversarial Networks (GAN)

O Sensor-near simulation models of all active sensors

O Synthetic inclement weather datasets for Al

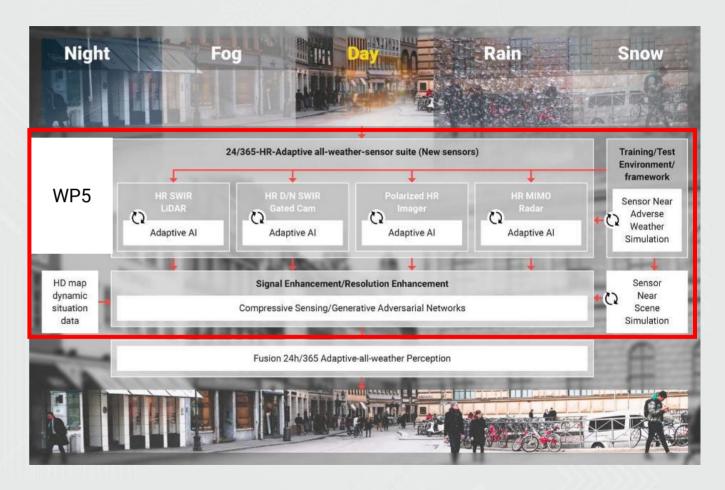


SIMULATION AND VALIDATION

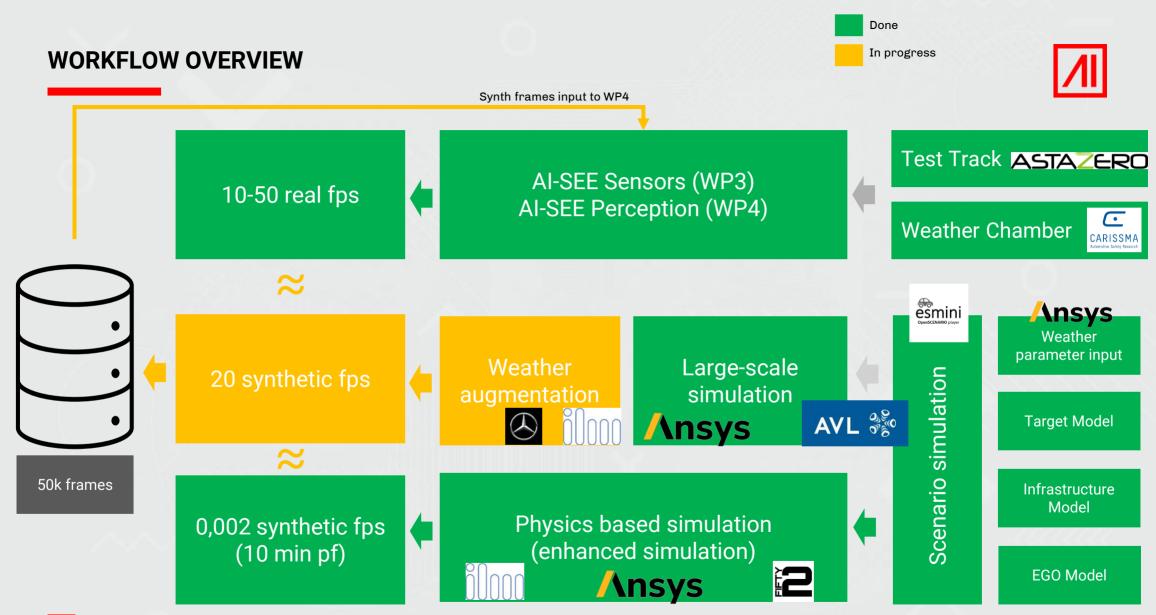
WP5 - SIMULATION AND VALIDATION



- Specification/Setup of a Simulation Platform
- Modelling of inclement weather environment
- Modelling of the new sensor suite
- Modelling of static und dynamic scenarios
- Generation of Synthetic Sensor Raw Data by Simulation
- Validate Simulation results versus static Lab Measurements
- Validate Simulation results versus dynamic Scenarios on test tracks



WP: Work Package



MAGNIFYING GLASS: SIMULATION SETUP - 3D SCENE Assets: **Carissma Hall Scene Setup:** CAR-PAINT-ValloireWhite1600 **Ceiling Lamps:** Luminous FLUX: Rearlamp: 925600lm Lambertian 60 deg Spektrum: CIE daylight Spektrum: Gaussian Red fluorescent lamp Wall: 7023-Concrete Gray **CAR-PAINT-Black** Floor: RL_Road_10% Headlamp Low Beam IES \nsvs **Mercedes EGO Vehicle FOV:** Stereo Camera: OnSemi Aptina **AR0230AT** Headlamp Low Beam IES

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MAGNIFYING GLASS WORKFLOW: NIGHT-RAINY-WET





Measured Camera Image

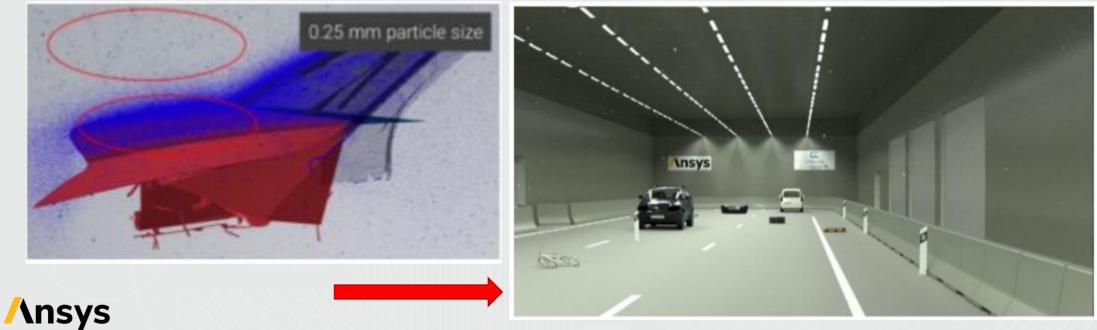
Simulation result (specular material + normal map texture)



MAGNIFYING GLASS WORKFLOW: PREONLAB - SPEOS COUPLING



• Workflow for coupling between PreonLab and Ansys SPEOS





Ray tracing with Ansys Speos



VALIDATION – MAGNIFIER WORKFLOW EXAMPLE







Dry Scenario - Daylight





Rain Scenario - night





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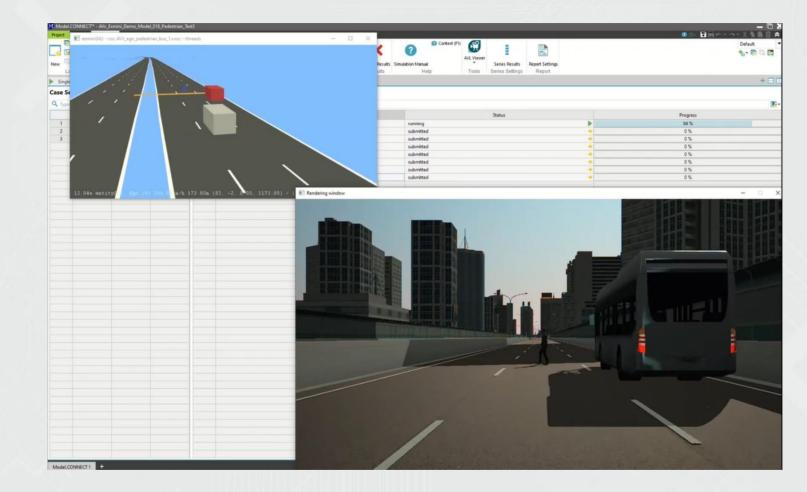
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Fog Scenario - night

VIRTUAL DATA SIMULATION - LARGE SCALE WORKFLOW - DEMO





Link to the Video



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FACTS & NUMBERS



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COORDINATOR

20 PARTNERS

OEMs, Automotive Suppliers, Research Institutes, **Engineering Companies**



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43 MONTHS RUNTIME

01.06.2021-31.12.2024

6 COUNTRIES

Austria, Canada, Finland, Germany, Israel, Sweden

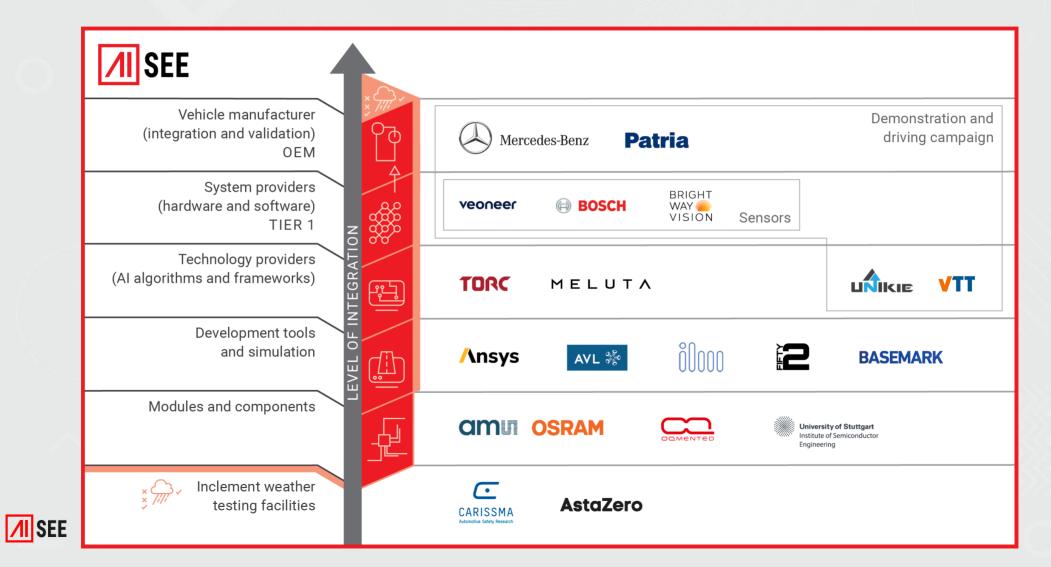
€20M Total costs

€10M Funding budget



CONSORTIUM OVERVIEW





CONSORTIUM OVERVIEW







THANK YOU VERY MUCH FOR YOUR ATTENTION!

CONTACT US



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