

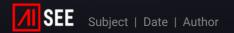
ARTIFICIAL INTELLIGENCE ENHANCING VEHICLE VISION IN LOW VISIBILITY CONDITIONS

Add your company name here Add your name here

STATUS: 05.04.2022



HOW CAN WE ENSURE THAT **AUTOMATED VEHICLES DRIVE RELIABLY** EVEN IN ADVERSE WEATHER CONDITIONS?









THE GOAL



Develop a robust and fault-tolerant novel sensing technology and associated AI

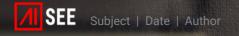
Enable automated driving in all relevant
weather & lighting conditions (snow, heavy rain, fog)

Permit safe driving **24h / 365-days**



THE CHALLENGE





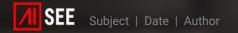
THE CHALLENGE



• Currently commercialization of automated vehicles is difficult due to their inability to drive under any relevant weather and lighting conditions.

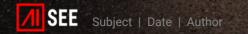
• Testing takes place in **small designated areas with good** weather conditions.

• Prototypes **struggle or completely fail** in adverse weather.



THE INNOVATION

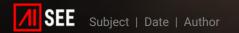




THE INNOVATION



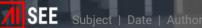
- AI-SEE will **prepare the broad market entry of automated vehicles** building a robust and safe perception system operating in all relevant weather and lighting conditions.
- It will extend the Operational Design Domain (ODD) of today's systems that assist the driver or provide conditional automation to full self-driving capabilities.
- Through extensive testing in adverse weather under real traffic scenarios the project will make prototypes functional in real driving conditions.



PROJECT OBJECTIVE



Night

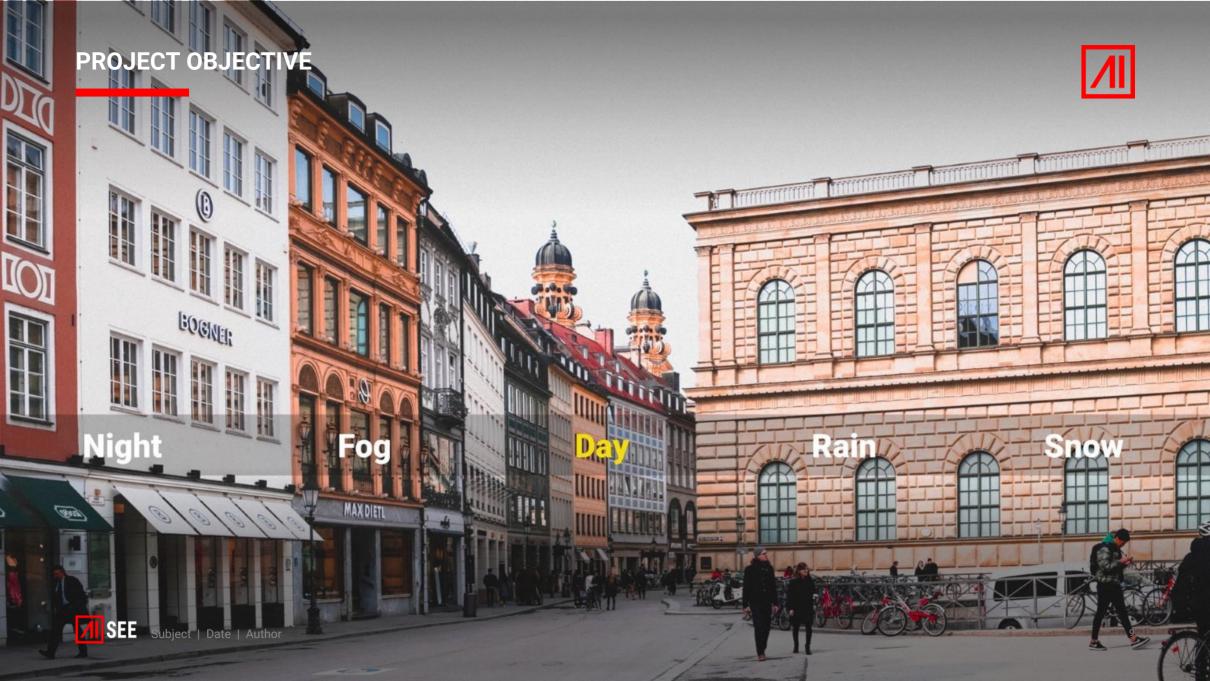


Fog

Lu







PROJECT OBJECTIVE

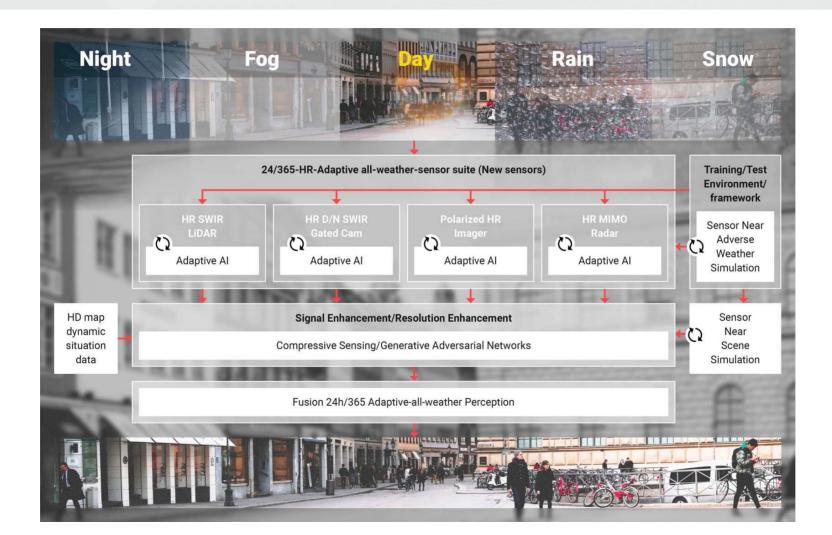


EXTEND THE OPERATIONAL DESIGN DOMAIN (ODD) OF AUTOMATED VEHICLES TO ALL WEATHER AND VISIBILITY CONDITIONS EXPERIENCED 365 DAYS OF THE YEAR



THE CONCEPT





THE CONCEPT



• High resolution adaptive all-weather sensor suite with novel sensors

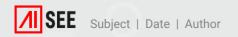
• Al platform for predictive detection of prevailing environmental conditions including signal enhancement and sensor adaptation

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 Novel simulation path which allows to realistically simulate adverse weather near the sensor to adapt and test the system on both real and artificially generated road scenes

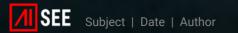
O High definition maps with dynamic layers adaptable to changing weather conditions

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24 / 365 HIGH RESOLUTION ADAPTIVE ALL WEATHER SENSOR SUITE



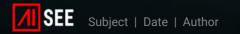


24 / 365 HIGH RESOLUTION ADAPTIVE ALL WEATHER SENSOR SUITE

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The all-weather multi-sensor suite will include the development of:

- a gated SWIR-camera that will enable a post-processing pixel-level depth estimation
- a short-wave infrared (SWIR) LiDAR with a novel SPAD receiver architecture
- a PolCAM active polarimetric imager with congruent LiDAR data
- a high resolution 4D MIMO Radar prototype with a dense point cloud
- a high definition dynamic map to support environment perception



ALL WEATHER MULTI-SENSOR PERCEPTION SYSTEM SUPPORTED BY AI





ALL WEATHER MULTI-SENSOR PERCEPTION SYSTEM SUPPORTED BY AI



The AI platform will include the development of:

Multisensory data fusion approach: Deep Sparse Multi-Scale Convolutional Neural Networks

Predictive detection of prevailing environmental conditions and sensor adaptation

Signal enhancement via Generative Adversarial Networks (GAN)

Sensor-near simulation models of all active sensors

Synthetic inclement weather datasets for AI

FROM **DENSE** TO AI-SEE





AI-SEE will take up the results of the predecessor EU-funded project DENSE.

The environment perception system developed in DENSE will be improved to simulate sensor output under adverse weather and to adapt and test the system on artificial data.

TESTING CAMPAIGNS & DATA COLLECTION

SEE Subject | Date | Author

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Source: AstaZero

TESTING CAMPAIGNS & DATA COLLECTION

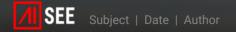


TESTING CAMPAIGNS

- **Testing campaigns** for sensor and perception validation in real traffic scenarios and in the partners' fog and rain chambers will be carried out.
- The **testing will ensure** that the prototypes will be functional in real driving conditions.

DATA COLLECTION

- **Sensor framework** mounted in the North: automatic data recording triggered by inclement weather.
- **Outdoors measurement** in series of test drives in Northern Europe.



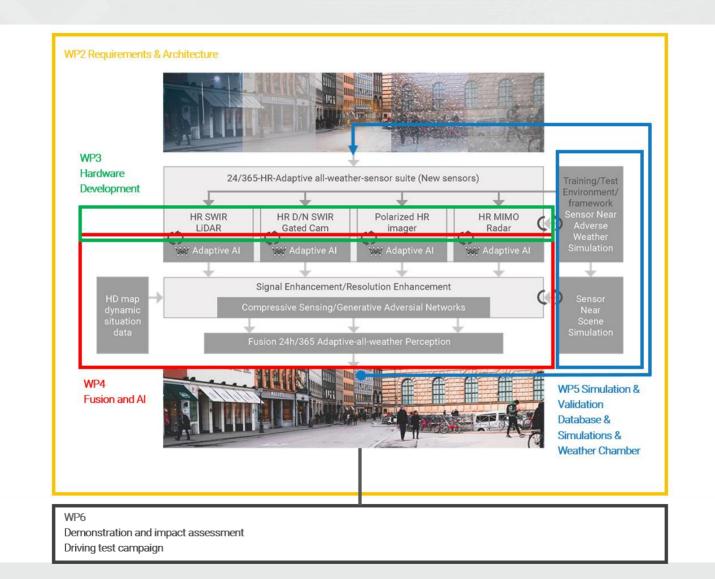
THE IMPACT





THE STRUCTURE





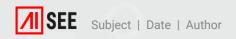


THE STRUCTURE



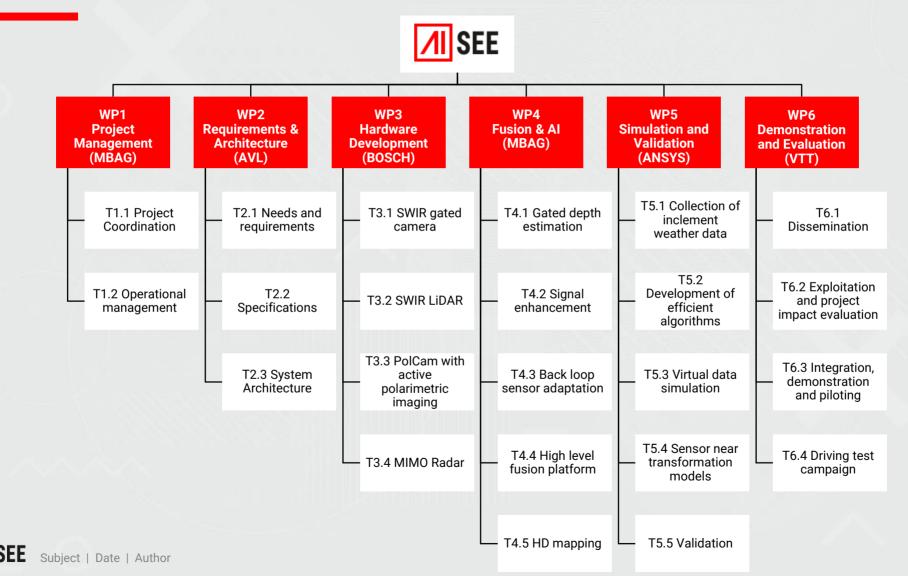
WP1- Project Management			
WP2	WP3	WP4	WP5
Requirements &	Hardware	Fusion	Simulation &
Architecture	Development	& Al	Validation

WP6 - Demonstration, Exploitation and Evaluation



THE STRUCTURE





FACTS & NUMBERS



COORDINATOR

Dr. Werner Ritter Mercedes Benz AG



20 PARTNERS

OEMs, Automotive Suppliers, Research Institutes, **Engineering Companies**



43 MONTHS RUNTIME

01.06.2021-31.12.2024

6 COUNTRIES

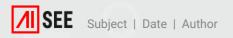
Austria, Canada, Finland, Germany, Israel, Sweden E

€20M

Total costs

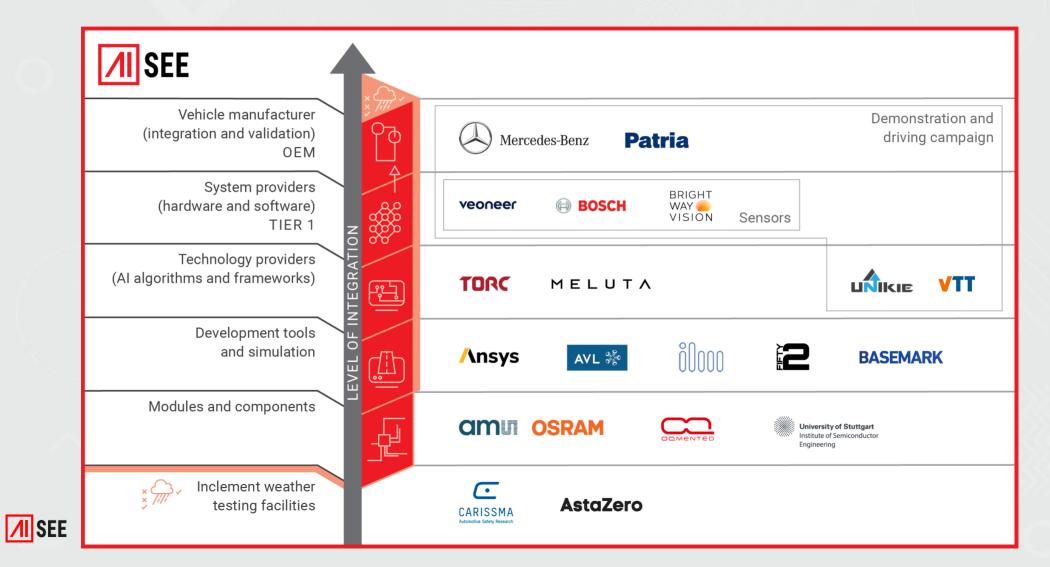
€10M F

Funding budget



CONSORTIUM OVERVIEW

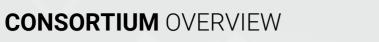




OEMs

BRIGHT BOSCH

SYSTEM PROVIDERS (HARDWARE & SOFTWARE)







CONTACT US



MORE INFORMATION ABOUT THE PROJECT:

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THANK YOU VERY MUCH FOR YOUR ATTENTION!